

Seismic Analysis of Tall Building with Central Core as Tube Structure

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Abstract: - A High Rise building with 25 floors having a centralized shear core is analyzed for earthquake loads with respect to a RC Frame Structure having same number of storeys. Comparison is made among the 8 configurations of the same building plan which are: Rigid Frame, Rigid Frame with central shear wall, Tube in Tube Structure, Tube Mega Frame Structure, Suspended Structure, Trussed Tube, Tube in Tube with Outriggers & Frame with central core and outriggers & belt truss. The usefulness of shear walls in the structural planning of multi-storey buildings has long been recognized. Incorporation of shear wall has become inevitable in multi-storey building to resist lateral forces. The buildings have been modeled using ETABS software for earthquake zone V in India. This paper aims to determine the effect of seismic loads, to study the lateral storey displacement, story drift and base shear, Story shear and time period for rigid frame, frame shear wall, braced frame, suspended structure, tube-in-tube and tubed mega framed structure. Dynamic responses under zone V earthquake as per IS 1893 (part 1): 2016 have been carried out. In dynamic analysis, Response Spectrum method is used.

Key Words:— *Shear Core, Response Spectrum, High Rise, ETABS, Seismic, drift, shear, time period.*

I. INTRODUCTION

A. Background

A high rise building provides effective way for the residential and commercial use. Apart from these advantages, a high rise building becomes landmarks of a city to signify the whole world. Different types of structural systems are to be used to resist the effect of lateral loads on the buildings. They are rigid frame structures, braced frame structures, shear wall frame structures, outrigger systems, and tubular structures. Out of these the tubular systems are extensively used and which is considered as a better lateral structural systems for high rise buildings. The tubular structures are further classified as frame tube, braced tube, bundled tube, tube in tube, and tube mega frame structures. The tube in tube structures and tube mega frame structures are the innovative and fresh concept in the tubular structures. The tube in tube structures are to be widely used in tall buildings. And the tubed mega frame structures are the new concept in the field of tubular structures for tall buildings. Generally, Tube in tube structures are formed by connecting peripheral frame tube and inner core tube. These tubes are interconnected by system of floor slabs and grid beams.as the columns of outer and inner core tubes are placed so closely; it is not seen as a solid system but it acts like a solid surface. In the tube in tube structure the high strength concrete central tube carries the major load. The total loads acting on the structures to be collectively shared between the inner and outer tubes. The tubed mega frames are new concept for tall building. It is formed by avoiding central core tube and peripheral tubes connected by perimeter wall

instead of one central core. The main function of perimeter wall is to transfer load between the long vertical tubes. In tubed mega frames instead of one central tube several vertical tubes are carrying the lateral loads. And the space utilization is maximum in tubed mega frames compare to tube in tube structure.

B. Lateral load resisting systems

Lateral load resisting systems are structural elements which resist seismic, wind and eccentric gravity loads. There are a lot of different systems but they can be broken down to three fundamental ones which all other systems are a combination of. They are:

- Shear walls
- Moment resisting frames
- Braced frames

C. Structural System in High Rise Building

The two primary types of vertical load resisting elements of tall buildings are columns and walls, the later acting either independently as a shear walls or in assemblies as shear wall cores. The building function will lead naturally to the provision of all to divide and enclose space, and cores to contain and convey services such as elevators. Column will be provided, in otherwise unsupported regions, to transmit gravity loads and, in some types of structures horizontal loads.

D. Shear wall – frame buildings

A Shear Wall is a structural system composed of braced panels (also known as shear panels) to counter the effects of lateral load acting on a structure. Wind and seismic loads are the most common loads that shear walls are designed to carry. Depending on the size of the building some interior walls must be braced as well. The main function of shear walls for the type of structure being considered here is to increase the rigidity for lateral load resistance. Shear walls also resist vertical load, and the difference between a column and a shear wall may not always be obvious. The distinguishing features are the much higher moment of inertia of the shear wall than a column and the width of the shear wall, which is not negligible in comparison with the span of adjacent beams

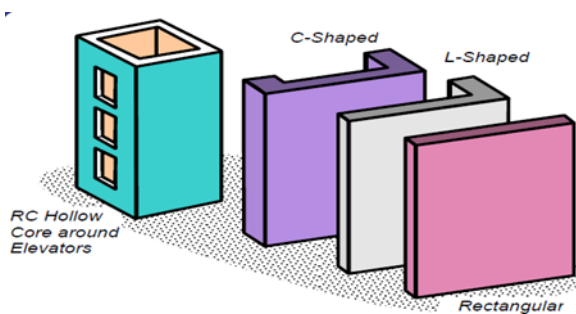


Figure.1.1. Various Types of Shear Walls

E. Braced rigid frame

If the braced frame, or shear walls, and a rigid frame are combined, it produces a greater amount of lateral stiffness. This is because of the way the two systems react to the horizontal loads. With the moment frames shear deformation and the bracing's bending deformation the combined deformation is more efficient, as shown in Figure.1.3. Instead of continuing to bend at the top the rigid frame keeps the shear wall or braced frame in place, while at the bottom the bracing, or wall, is restraining the shear deformation of the moment frame. This results in a deflection with an "S" shape

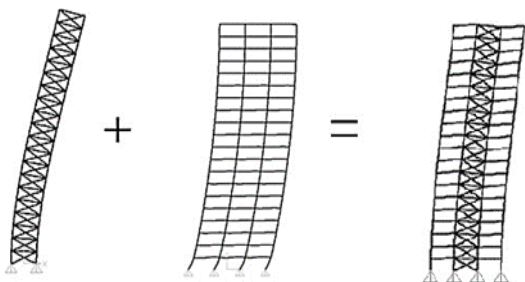


Figure.1.2. A braced frame combined with a rigid frame will decrease a buildings deflection

F. Tubular design

In the 1960's Fazlur Khan discovered that the steel frame systems were not the only way to stabilize high-rise buildings. By looking at a building as a vertically standing hollow box, cantilevering out of the ground, he discovered the tube design. As a theoretical idea he pictured the walls around the building being solid, later adding openings for windows for a workable application. This analysis showed that even with openings this structural form would provide a lot in terms of lateral resistance. This is because when the walls are connected as a box it will fully utilize the outer perimeter walls in every direction; see Figure 1.4 and following page. Elementary beam theory indicates that the elements farthest away from the central axis will be the most utilized in supporting the structures bending loads and obtaining greater stiffness. Along with providing lateral stiffness the perimeter is often designed to take a larger part of the vertical load than before. With more vertical load in the perimeter the buildings ability to resist overturning increases. Khan's discovery of the tube offered a few new variations such as the framed tube, trussed tube and the bundled tube. (Khan, 2004)

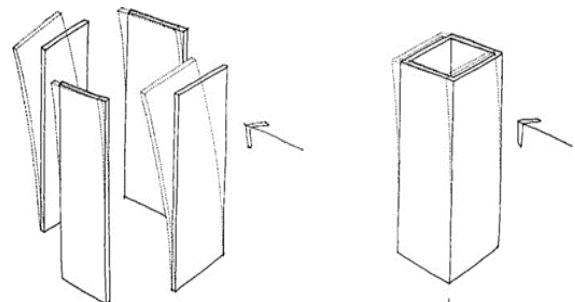


Figure 1.3 When subjected to wind loads, unconnected walls will bend around their weak axis offering little resistance. If connected to a tube, the walls will participate together in resisting the load. The effectiveness will increase significantly (Khan, 2004)

II. METHODOLOGY

A. Essentials of Structural Systems for Seismic Resistance

The primary purpose of all structural members used in buildings is to support gravity loads. However, buildings may also be subjected to lateral forces due to wind and earthquakes. The effects of lateral forces in buildings will be more significant as the building height increases. All structural systems will not behave equally under seismic excitation. Aspects of structural configuration, symmetry,

mass distribution and vertical regularity must be considered. In addition to that, the importance of strength, stiffness and ductility in relation to acceptable response must be evaluated in structural system (Paulay and Priestley, 1992). The first task of the structural designer is to select the appropriate structural system for the satisfactory seismic performance of the building within the constraints dictated by architectural requirements. It is better where possible to discuss architect and structural engineer for alternative structural configuration at the earliest stage of concept development. Thus, undesirable geometry is not locked into the system before structural design is started. Irregularities in buildings contribute to complexity of structural behavior. When not recognized, they may result in unexpected damage and even collapse of the structures. There are many possible sources of structural irregularities. Drastic changes in geometry, interruptions in load path, discontinuities in both strength and stiffness, disruption in critical region by openings and unusual proportion of members are few of the possibilities. The recognition of many of these irregularities and of conceptions for remedial measures for the mitigation of their undesired effects relies on sound understanding of structural behavior.

B. Response Spectrum Method

In order to perform the seismic analysis and design of a structure to be built at a particular location, the actual time history record is required. However, it is not possible to have such records at each and every location. Further, the seismic analysis of structures cannot be carried out simply based on the peak value of the ground acceleration as the response of the structure depend upon the frequency content of ground motion and its own dynamic properties. To overcome the above difficulties, earthquake response spectrum is the most popular tool in the seismic analysis of structures. There are computational advantages in using the response spectrum method of seismic analysis for prediction of displacements and member forces in structural systems. The method involves the calculation of only the maximum values of the displacements and member forces in each mode of vibration using smooth design spectra that are the average of several earthquake motions. This deals with response spectrum method and its application to various types of the structures. The codal provisions as per IS 1893 (Part 1): 2016 code for response spectrum analysis of multi-story building is also summarized.

C. Details of the Building

A symmetrical building of plan 32m X 32m located with location in zone V, India is considered. Eight bays of length 4m along X - direction Y - direction are provided. Shear Wall is provided at the center core.

Table.2.1. Details of the building

Building Parameters	Details
Type of frame	Special RC moment resisting frame fixed at the base
Building plan	32m X 32m
Number of storeys	25
Length of span in X direction	4m
Length of span in Y direction	4m
Floor height	3.0 m
Depth of Slab	150 mm
Size of beam	(300 × 800) mm
Size of column	(exterior) (800 × 800) mm
Size of column	(interior) (800 × 800) mm
Live load on floor	2 KN/m ²
Floor finish	1.0 KN/m ²
Wall load (230mm brick wall)	13.8 KN/m
Grade of Concrete	M 40 concrete
Grade of Steel	Fe500
Thickness of shear wall	400mm
Bracing section	ISMC 300
Density of concrete	25 KN/m ³
Damping of structure	5 percent

Table 2.2. Details of seismic parameters

Seismic Parameters	Details
Seismic zone	V
Importance factor	1.2
Response reduction factor	5
Type of soil	Medium
Response spectra	As per IS 1893(Part-1):2016
Damping of structure	5 percent

III. MODELING OF BUILDING

A. Model Design

One of the objectives of this model generation is to ensure that the models represent the characteristics of residential buildings. High-rise buildings are different in shape, height and functions. This makes each building characteristics different from each other. There are some standards for each kind of high-rise buildings, such as residential, office and commercials. However, for model generation, main factors such as column layout, grid spacing, floor shape, floor height, mass and stiffness irregularity, and column orientation were considered. Mostly in Residential buildings, floor plan will be same for all floors. Shear walls of same section were used for same height of buildings throughout the height. In this study a high rise multi-storey building is studied for building with shear walls provided at the centre core. The buildings are modeled using software ETABS. Dynamic analysis is carried out for this case.

B. Structural Modeling of Building

To study the effects of central core on seismic responses of buildings, three dimensional (3D) geometric models of the buildings were developed in ETABS. Beams and columns were modeled as frame elements. Shear walls were modeled as plate elements. Floor slabs were modeled as rigid horizontal plane. Due to time limitations, it was impossible to account accurately for all aspects of behavior of all the components and materials even if their sizes and properties were known. Thus, for simplicity, following assumptions were made for the structural modeling:

- The materials of the structure were assumed as homogeneous, isotropic and linearly elastic.
- The effects of secondary structural components and nonstructural components such as staircase, masonry infill walls were assumed to be negligible.
- Floors slabs were assumed rigid in plane.
- Foundation for analysis was considered as rigid.

C. Layout of the Buildings

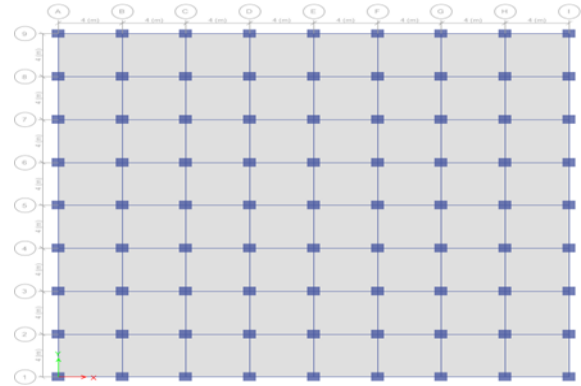


Fig.3.1 Plan of Rigid Frame

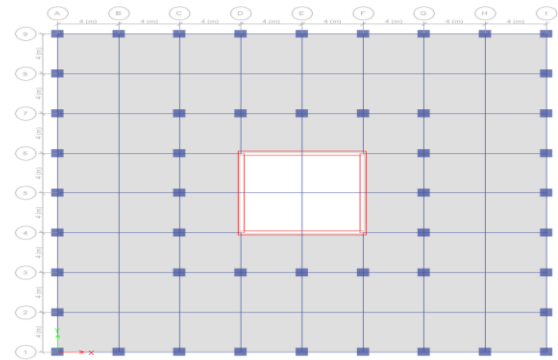


Fig.3.2 Plan of Frame with central shear wall core

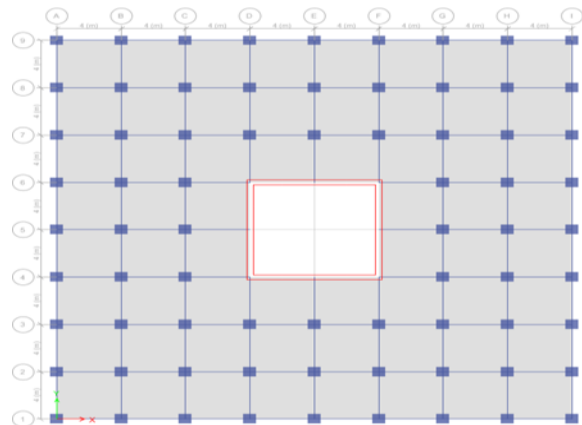


Fig.3.3 Plan of Tube in tube frame

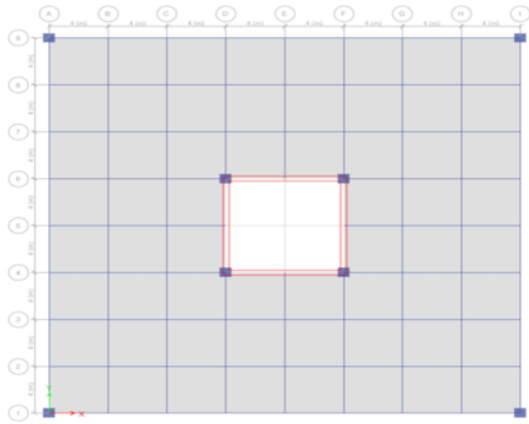


Fig.3.4 Plan of Tubed mega frame structure

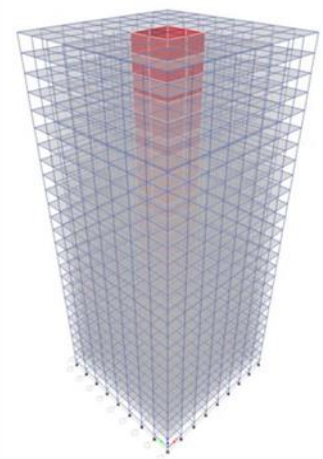
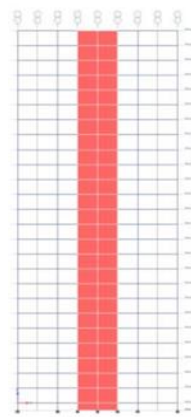


Figure 3.7 Tube in tube structure

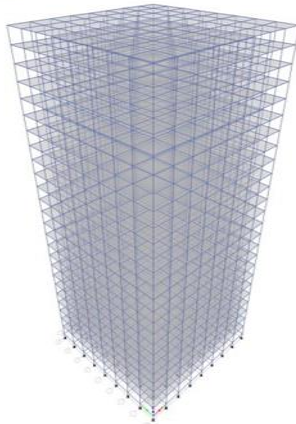
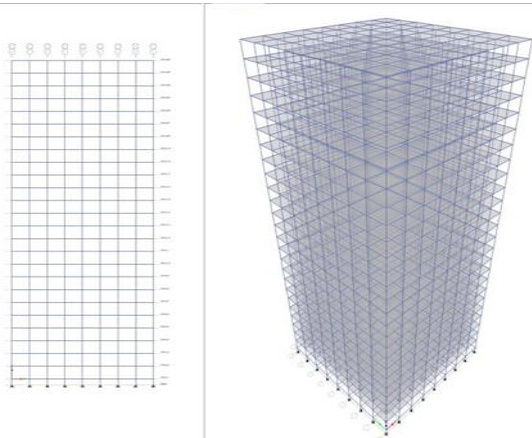


Figure 3.5 Rigid Frame

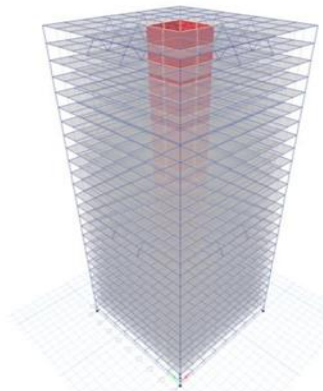
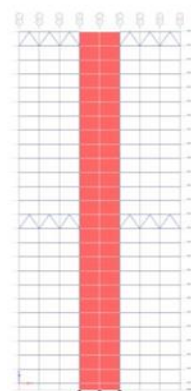


Figure 3.8 Tubed mega frame structure

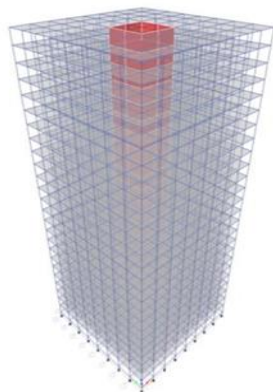
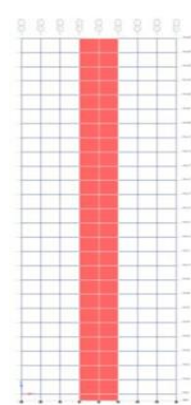


Figure 3.6 Rigid Frame with central shear wall

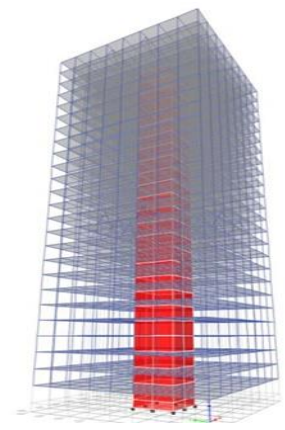
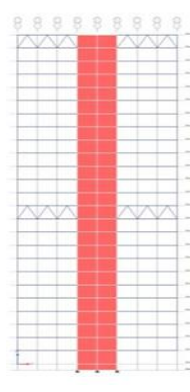


Figure.3.9 Suspended Tube Structure

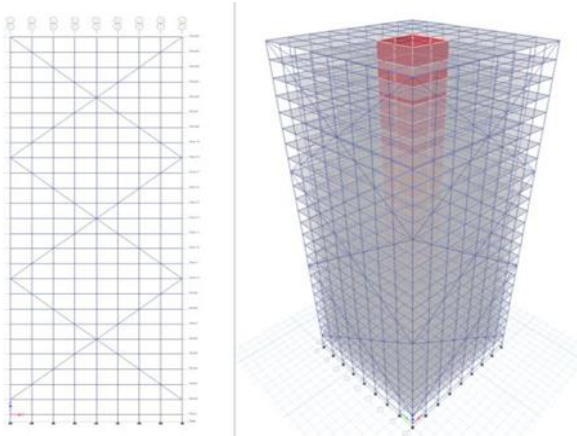


Figure 3.10 Trussed Tube

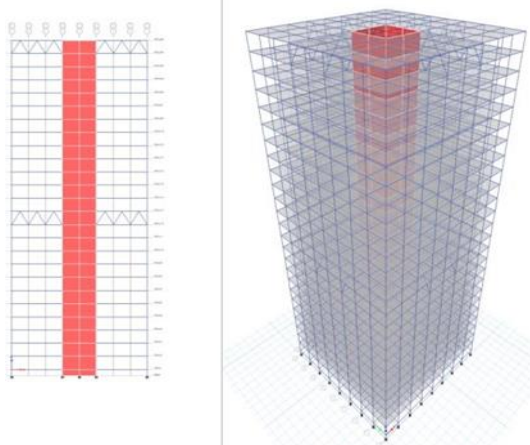


Figure 3.11 Tube in tube with outriggers

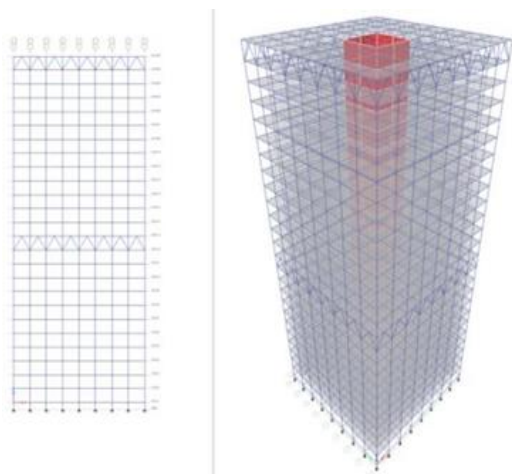


Figure 3.12 Frame with central core and outriggers & belt truss

D. Building Design Requirements

The proposed reinforced concrete shear wall buildings are located in zone V, India. Code requirements from IS 456: 2000, and IS 1893 (part 1): 2016 were used for structural design.

In the ETABS design model, modeling was done in order to verify sufficient strength and stiffness. Rigid diaphragms, along with lumped masses, were assigned at each level.

E. Load Combinations

As per IS 1893 (Part 1): 2016 Clause no. 6.3. the following load cases have to be considered for analysis:

1.5 (DL + IL)

1.2 (DL + IL ± EL)

1.5 (DL ± EL)

0.9 DL ± 1.5 EL

Earthquake load must be considered for +X, -X, +Y and -Y directions.

F. Structural Analysis

Initial dimensions of the structural elements for the buildings were assumed on the basis of gravity loads and imposed loads. Since, the buildings were assumed as apartment buildings, imposed load of 2 kN/m² and load due to floor finish were taken as 1.0 kN/m² as per Indian Standard, IS 875 (part2): 1987. Lateral loads due to earthquake (EL) were calculated considering full dead load (DL) plus 25% of imposed load (IL), using seismic coefficient method given in IS 1893 (Part 1): 2016.

Since the buildings were assumed as apartment buildings with dual system (shear wall and special moment resisting frame) situated in seismic zone V,

Importance factor (I) = 1.2, Zone factor (Z) = 0.36 and

Response reduction factor (R) = 5 as given in IS code -1893 were used for lateral load calculations. Assuming medium type of soil on which the foundations rest and the damping ratio of 5% for concrete structure, average response acceleration coefficient (Sa/g) was obtained from depending on the approximate fundamental natural time period of the structure estimated

$$\text{by: } T_a = \frac{0.09h}{\sqrt{d}}$$

In which,

h= height of building in meter

d = base dimension of the building at plinth level, in meter, along the considered direction of lateral force

$$Q_i = VB \left\{ \frac{w_i h_i^n}{\sum_{j=1}^n w_j h_j^n} \right\}$$

Q_i = Design lateral force at floor i

W_i = seismic weight of floor i

h_i = height of floor i measured from base, and

n = number of stories in the building, is the number of levels at which masses are located assuming the floor is capable of providing rigid diaphragm action (floor to be infinitely rigid in the horizontal plane), total shear in any horizontal plane is distributed to the various vertical elements according to their relative stiffness.

After several analyses in ETABS using equivalent static lateral force analysis for various load combinations given in IS 1893 (Part 1): 2016, final dimensions of the structural elements for further analyses of the buildings were obtained.

The maximum percentage of reinforcements for structural elements was limited to 4% of concrete gross area as per IS 456: 2000.

Concrete grade of M40 i.e. characteristic compressive strength (f_{ck}) of 40 N/mm² was assumed for all structural elements. Material properties were assumed same for all structural elements used in both all the buildings. The material properties assumed for final structural analysis are as follows:

Modulus of elasticity (E) = 31.62 × 10⁶ kN/m² Poisson's ratio (ν) = 0.15

Unit weight of concrete (γ) = 25 kN/m³

IV. RESULT AND DISCUSSIONS

The behavior of each model is studied and the results are tabulated. The variation of systematic parameters like base shear, lateral displacement, story drift, natural time period, axial force, shear force and moments in column and shear force, torsion and moment in beam has been studied for response spectrum analysis method.

A. Results of Base shear for all models

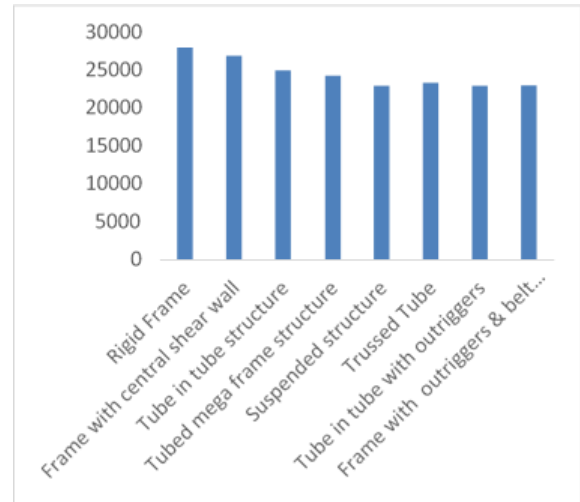


Figure 4.1 Comparison of Base shear

Figure 4.1 shows comparison of base shear for all eight models. It shows that base shear is maximum in rigid frame without central shear wall core and minimum in suspended structure with central shear wall core. By adding central shear wall core base shear is reduced in all models other than rigid frame up to 10% to 25%.

B. Results of maximum lateral displacement for all models

Figure 4.2 shows comparison of maximum lateral displacement for all eight models. It shows that lateral displacement is maximum in suspended structure with central shear wall core and minimum in frame with central shear wall core. By adding central shear wall core lateral displacement is reduced in rigid frame and tube in tube structure. But in tubed mega frame and suspended structure

Model 1	Rigid Frame
Model 2	Frame with central shear wall
Model 3	Tube in tube structure
Model 4	Tubed mega frame structure
Model 5	Suspended structure
Model 6	Trussed Tube
Model 7	Tube in tube with outriggers
Model 8	Frame with outriggers & belt truss

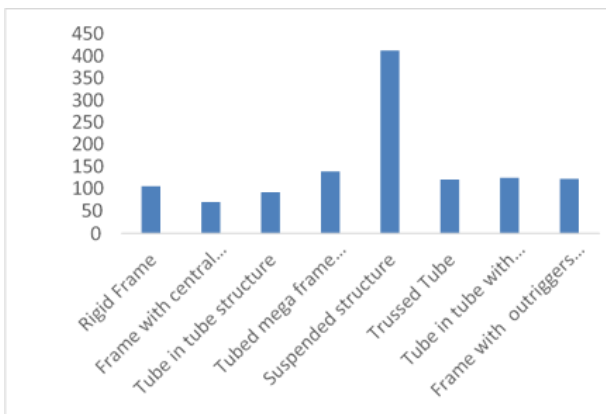


Figure 4.2 Comparison of maximum lateral displacement displacement is increased drastically which is about 80%. By providing truss in outer frame, displacement is controlled but still high is increased up to 30% as compared to frame with central core. It is because of columns are provided in outer perimeter only in tubed structure.

C. Results of natural time period for all models



Figure 4.3 Comparison of natural time period

Figure 4.3 shows comparison of natural time period for all eight models. It shows that time period is maximum in suspended structure with central shear wall core and minimum in rigid frame with central core. This is due to central shear wall core in rigid frame added extra stiffness in structure which reduced lateral displacement thus reducing oscillation period of structure. Though other tubed frame having central core, but columns only in outer perimeter reduces stability of structure increasing oscillation period of structure.

D. Results of storey drift for all models

Figure 4.4 shows comparison of storey drift for all eight models. It shows that storey drift is maximum in suspended structure with central shear wall core and minimum in rigid frame with central core. This is due to central shear wall core in rigid frame added extra stiffness

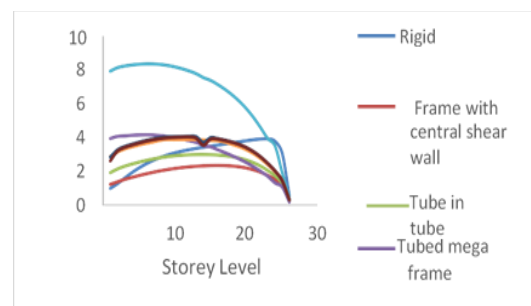


Figure 4.4 Comparison of storey drift

in structure which reduced lateral displacement thus reducing storey drift ratio of structure. Though other tubed frame having central core, but columns only in outer perimeter reduces stability of structure increasing storey drift ratio of structure.

E. Results of axial force in column for all models

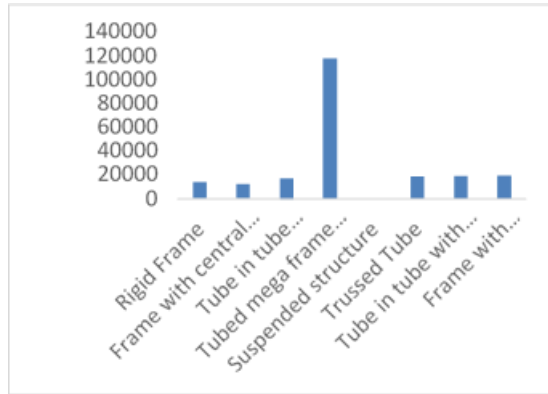


Figure 4.5 Comparison of axial force in column

Figure 4.5 shows comparison of axial force in column for all eight models. It shows that axial force is maximum in tubed mega frame with central shear wall core and minimum in suspended structure with central core. This is due to tubed mega frame having only four columns at corner of 3 times increased size of design section carrying highest axial force in column. While in suspended structure all weight of structure is concentrated on central core and less force is passing through column. Axial force in column of tubed mega frame is increased upto 90% than in frame with central core.

F. Results of shear force in beams for all models

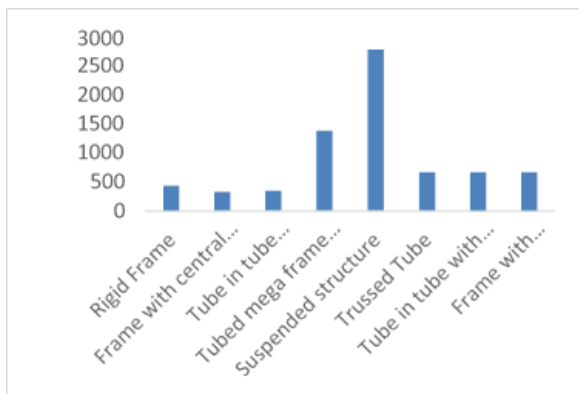


Figure 4.6 Comparison of shear force in beam

Figure 4.6 shows comparison of shear force in beam for all eight models. It shows that shear force is maximum in tubed mega frame and suspended structure with central shear wall core. It is minimum in frame with central core. Shear force in

tubed mega frame is increased upto 50% and in suspended structure is increased upto 85% than other models.

V. CONCLUSION AND FUTURE STUDY

It is not a simple task to determine which of the stabilization system that is most effective because there appears to be no universal solution to meet all possible requirements that may arise. Some systems are best suited taking into account certain factors, but has disadvantages over others. Based on the analysis as discussed in chapter5 following conclusions can be drawn.

- From the previous study we can observed that rigid frame have maximum base shear against lateral seismic loading and other models with central core wall i.e. tube in tube, tubed mega frame, suspended structure, frame with outriggers and truss shows gradually decreasing base shear.
- From the previous study we can observed that rigid frame with central core wall will get maximum reduction in displacement and drift. Whereas suspended structure with core wall shows drastically increasing displacement and drift as whole weight of structure stabilized on central core wall.
- Natural time period for tubed mega frame and suspended structure are more than other models.
- Axial force, shear force and moments in column are very high in both tubed mega frame structure and suspended structure. Also shear force and moments in beam are maximum in both structure.
- Hence, practically tubed mega frame and suspended structure are not economic structure. Also these structure cannot be efficiently designed against lateral seismic loading.
- On other hand, by adding central core wall in rigid frame and tube in tube structure behaves efficiently against lateral loading because of increased stiffness.
- From the results depicts that Outrigger and belt truss one of the efficient resisting system against lateral load used in the multistory buildings. But abrupt changes in the number of column in geometry reduces the stiffness of the building.

Future Study:

- The study can be extended for steel and composite multistoried building.
- Different plan geometry can be considered for further study.

- Here analysis is done with response spectrum method. Further analysis can be done with time history method and comparative results can be plot.
- Quantity of concrete and steel can be find out and do cost estimation of material.

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Agriculture in India constitutes more than 60% of the occupation. It serves to be the backbone of Indian economy. It is very important to improve the efficiency and productivity of agriculture using new technology available with engineers. Earlier method requires more labours, more time, more cost and energy consuming. Whereas farming based on drilling operators of such power units are exposed to high level of noise and vibration, which are detrimental to health and work performance. In India there are 9.87 million farmers available so this agriculture vehicle with multiple operations will be helping them undoubtedly.

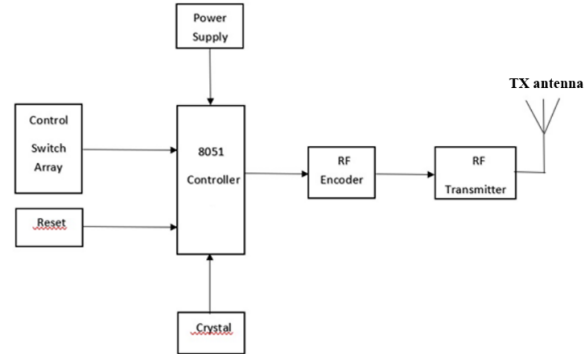
The farmers using Conventional methods to do the farming which was time taking and cost them more labours. The agriculture vehicle performs agricultural operations autonomously such as ploughing, seeding and water spraying these allowing farmers to reduce the environmental impact, increase precision and efficiency, and manage individual plants in novel ways. The applications of agriculture vehicle are spreading every day to cover further domains, also replacing human operators with autonomous vehicles which provides effective solutions with return on investment. This is especially important when the task that has to be performed is potentially harmful for the safety or the health of the workers. The vehicle is using RF Technology is something that is very new to the agriculture industry, but is quickly gaining popularity from agriculture research companies. RF wireless communication technology is used for control agriculture vehicle from distance, without human intervention. Implementing Also, the vehicle includes automatic watering the plant based on value of soil moisture sensor and detecting the obstacle using IR sensor. The IR sensors are configured with two modes which are manual and automatic modes.

VI. METHODOLOGY

Input to the proposed system is control switches and desired output is the execution of ploughing and sowing task. This execution in the project is achieved through mechanical parts. Two DC motors are used for driving the four wheels of vehicle, DC motors are required for movement of these vehicle, to rotate 360-degree angle, to move forward and back word direction. Other two DC motors are connected to L293D IC to enable ploughing and seeding parts rotation in both clockwise and anticlockwise direction. Relays are connected to DC motors of water pump and seed dropping.

Fig.1: Block diagram of Proposed system (Transmitter).

The Block Diagram of RF controller is as shown in Fig 4.6.



The 8951 controller is interfaced with the RF transmitter in the module, an array switches is used to provide command inputs to the 8951 microcontroller to perform the necessary operation. Control array switches will provide the commands to the micro controller. the control switches will provide the particular control input to the microcontroller so that the actuation operation is performed as per the requirement of the user. The user input from the switches will be received as a series of number to the microcontroller.

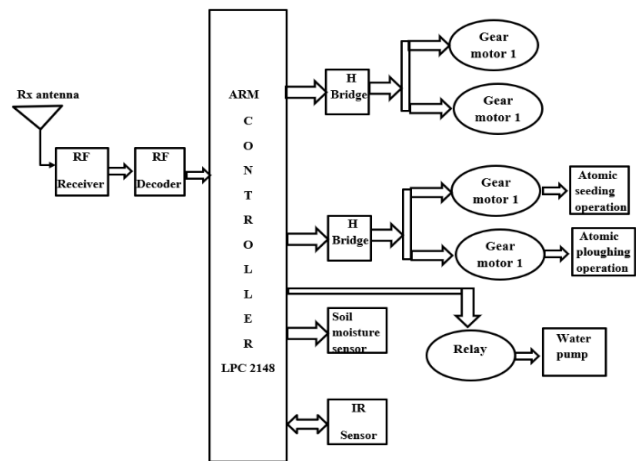


Fig.2: Block diagram of Proposed system (Receiver)

The Block diagram of proposed system is as shown in Fig 4.1. the RF Receiver gets the transmitted flag from the transmitter side, by utilizing ARM LPC2148 as its controller to work. It exhibits the progression of recipient task, LPC2148 is interfaced with RF Decoder, H-Bridge and hand-off LPC2148 ARM controller. H-bridge is an circuit which enables forward and backward operation of the DC electric motors. four geared motors are used two motors are used to control the moment of the vehicle and another geared motor is used to adjust the ploughing level

in the device and fourth geared motor is used for the seeding operation.

VII. IMPLEMENTATION

The steps followed during the process flow are as follows:

Step1: Initially the vehicle will check the moisture level of the soil using soil moisture sensor and differentiate weather the soil is wet or Dry.

Step2: The soil moisture sensor data is updated to the Arm controller.

Step3: Depending on the threshold of soil moisture sensor value, the water pump is automatically turned OFF. if the soil is wet and it will again continuously monitor the soil moisture data.

Step4: The ploughing and seeding functions will start after soil moisture sensing and depending on the input from sensor.

Step5: The vehicle is configured in two modes mainly automatic and manual mode, depending on the mode set by the user the Receiver will take the command inputs.

Step6: In automatic mode the vehicle will automatically detect the obstacle and move to the other direction by taking command input that is programmed.

Step7: In Manual mode the user will provide a command input to the vehicle, the vehicle will move manually depending on the input given by the intended user.

Fig.3: Flowchart of Proposed System

In automatic mode the Infrared sensor will continuously monitor for the obstacle. If any obstacle is detected the value input to the infrared sensor will changes. Depending on the changes in the value in the sensor the obstacle distance is calculated and the vehicle will automatically turn to other direction to avoid any damages.

In manual mode the user will give the command input to the vehicle through RF transmission and Reception of data. The vehicle is configured to move forward, backward, left and right moment of the vehicle depending the RF commands sent through the array of switches.

VIII. RESULTS AND DISCUSSION

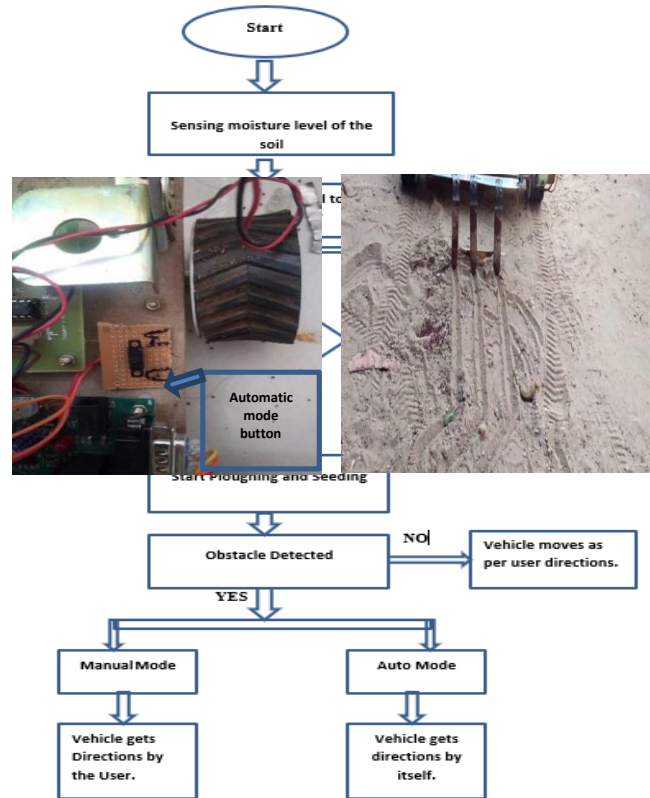
The Vehicle will work under 2 Modes.

- Automatic Mode
- Manual Mode

A. Automatic Mode

If the switch is in automatic mode, then the vehicle performs all the operation by itself such as the vehicle will

automatically take commands when an Obstacle is detected as shown in Fig, the vehicle is taking different path for Ploughing and seeding operation due to Obstacle detection.



The vehicle is developed which performs the operations such as seeding, ploughing and automatic water spraying. The seeding operation should be synchronized with the moment of vehicle so geared motor is used for efficient working of the vehicle.

Fig.4. Automatic Mode

B. Manual Mode

If the switch is in manual mode, then the vehicle and all operation is controlled by us.

An agriculture vehicle is developed which performs the operations such as seeding, ploughing and water spraying. The seeding operation should be synchronized with the

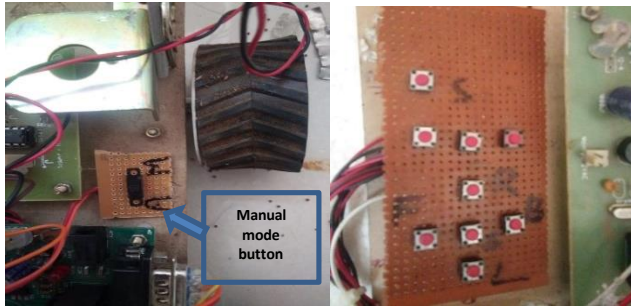


Fig.5. Manual Mode

moment of vehicle so geared motor is used for efficient working of the vehicle.

Depending on the soil moisture the water pump will automatically turned ON and OFF by the vehicle. If the soil is wet the water pump will be OFF. If the soil is Dry the water pump will be turned ON as shown in the Fig 6.



Fig.6. Water Supply based on Soil Moisture Sensor data

IX. CONCLUSION

The Proposed System will expand the utilization of cutting-edge innovation in the field of agribusiness, yet in addition to convey the innovation near the compass of farmers in money related angle, in an extremely helpful manner. It decreases certain monotonous work in agribusiness and thus urges numerous individuals to take up farming as an occupation. The vehicle is anything but difficult to work and is easy to understand. It additionally helps the farmers in hitting their objective of high efficiency.

In this project we implemented a water sprinkler for different crops by sensing moisture level of soil. We constructed a prototype model of multipurpose agriculture vehicle, which perform functions such as Ploughing, Seeding and Obstacle detection.

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